Machine Learning - Lecture 8: Decision trees

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Modeling involves finding and representing patterns in the data.

This means deciding what sort of pattern to look for, and how to represent it.

Learning methods always have a **bias** towards certain forms of pattern and representation.

A bias that is very specific is said to be **strong**.

Otherwise it is weak.

Because strongly biased methods are more focussed, they tend to be faster.

Weakly biased methods are more general.

A common problem in machine learning is bias mismatch.

This happens when the learning method is biased towards the wrong form of pattern, i.e., a form that does not feature in the data.

The result can be extremely bad performance in training or testing, or both.

- Clustering methods look for patterns which take the form of (hyper-)spherical groupings of similarly classified datapoints.
- This is a common form of regularity.
- But there are many contexts in which it is not seen.
- Applying clustering methods in such cases is likely to be ineffective.

#### Demo involving ebaySales data with k-means clustering.

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### Ebay-Sales dataset

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In the ebay data, we see data bunching-up in *rectangular* patterns.

This happens whenever specific values are significant in the classification of datapoints.

The effect is highly likely in categorical data.

It's also likely with numeric data whenever there are significant ranges or threshold values.

Applying centroid-based methods to data exibiting non-spherical forms of patterning, we have a bias mismatch that guarantees unsatisfactory results.

If we're not aware of what's going wrong, though, we may assume the answer is simply to increase the representational power of the method, i.e., increase the number of centroids.

The outcome can be then be confusing.

As we get closer to the situation of having one centroid per datapoint, performance on the training set improves.

But performance on testing data stays the same.

If we take this approach far enough, we end up with one centroid for each datapoint.

Performance on the training set is perfect.

But generalization is likely to be no better than would be achieved by random guessing.

We've fully replicated the data within the model.

The model then works as a kind of 'lookup table' for the data.

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Methods that are better suited for rectangular patterning are the decision-tree methods ID3, C4.5 and CART.

These incrementally construct a decision-tree, by repeatedly dividing up the data.

The aim at each stage is to associate specific targets (i.e., desired output values) with specific values of a particular variable.

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The result is a decision-tree in which each path identifies a *combination* of values associated with a particular prediction.

The effect achieved is representation of rectangular patterns.

### Worked example

The data represent files on a computer system.

The task is to derive a model for virus identification.

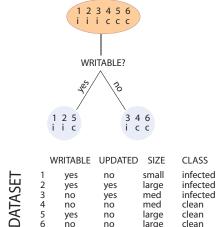
Possible values of the CLASS variable are 'infected', which implies the file has a virus infection, or 'clean' which implies that it doesn't.

		WRITABLE	UPDATED	SIZE	CLASS
ATASET	1 2 3 4 5	yes yes no no yes	no yes yes no no	small large med med large	infected infected infected clean clean
$\Box$	6	no	no	large	clean



	WR	ITABLE	UPDATED	SIZE	CLASS
DATASET	1	yes	no	small	infected
	2	yes	yes	large	infected
	3	no	yes	med	infected
	4	no	no	med	clean
	5	yes	no	large	clean
	5	no	no	large	clean

#### Evaluating possible splits



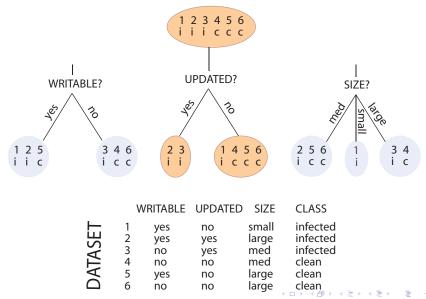
no

no

clean

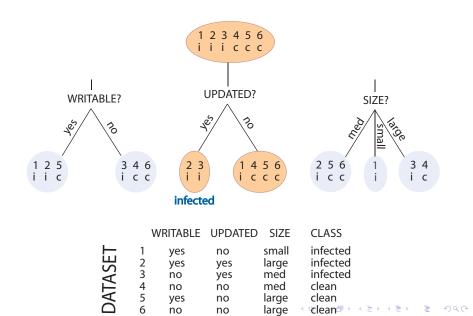
large

## Selecting the optimal split

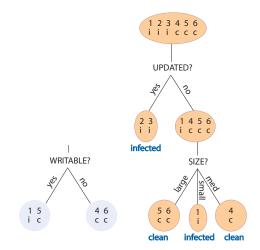


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### Creation of a terminal node

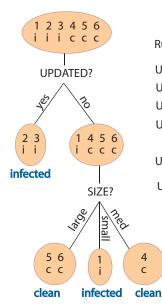


#### Finalised decision tree



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## Derived rules and implied facts



Rules derived from complete paths:

Using these rules we can infer facts such as

UPDATED=yes  $\land$  WRITABLE=no  $\land$  CLASS=infected

(1) Define the initial node of the decision tree to be the set of all data. Label it 'unfinished'.

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(6) Repeat from step 2.

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#### type data\golf

"Outlook	Temp	Humidity	Windy	Decision
sunny	75	70	true	Play
sunny	80	90	true	NoPlay
sunny	85	85	false	NoPlay
sunny	72	95	false	NoPlay
sunny	69	70	false	Play
overcast	72	90	true	Play
overcast	83	78	false	Play
overcast	64	65	true	Play
overcast	81	75	false	Play
rain	71	80	true	NoPlay
rain	65	70	true	NoPlay
rain	75	80	false	Play
rain	68	80	false	Play
rain	70	96	false	Play

```
java Id3 golf
Data: 10+4
Variable names: [Outlook Temp Humidity Windy Decision]
Most frequent output: Play
```

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```
Temp?
|-- <=83.0
| |-- Play
|-- >83.0
|-- NoPlay
```

Id3 #0 on golf R(10+4) 1.0 (100.0%)

# Summary

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## Questions

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